

# Advanced Gyro Stabilized Platforms and Motion Tables



Land - Sea - Air Applications

purpose directed & budget oriented



# Stabilisation - Detection - Tracking Multi Axes Platforms from simple Pan&Tilt heads up to high sophisticated solutions

Gyro stabilization is being used in applications such as steadying cameras mounted to helicopters or weapons being fired from mobile sources.

Coming from the inertial sensors and systems, iMAR is experienced also in controlling extreme conditions, such as extraordinary velocities and accelerations.

iMAR's gimbals are being designed and developed to military standards, such as MIL-STD-810G, MIL-STD-461G.

iMAR is a worldwide leading developer and producer of inertial systems for Navigation, Guidance, Control, Surveying and Stabilisation.



#### **Examples for iMAR's stabilized Gimbals**



- √ in-house design and manufacturing of complex mechanical structures
- ✓ suitable for land sea air environment
- √ recognition identification tracking
- ✓ up to ultra fast angular speed & acceleration
- ✓ versatile, also customzed designs
- ✓ all technological drive systems available (direct drives, gearbox motors, ...)
- ✓ payloads from few grams to several tons
- ✓ iSCU Interface for control via iOET<sup>2</sup> (video tracking), joystick, geo referencing IMS and external control computer

#### SEA BASED GIMBALS

- high precision stabilized marine gimbals
- designed with direct drive brushless torques and direct shaft mounted angular encoders for ultrahigh dynamics, high position resolution and accuracy and low wobble
- smooth stable rates over large dynamic range, suitable also for long focal length sensors
- continuous rotation in azimuth and elevation
- sliprings for optical video link (FORJ), UART RS422, Ethernet, RF rotary joint, discrete lines available
- designed for harsh naval environment
- integrated IMS or INS/GNSS for stabilization, control and geo-referencing



#### SINGLE AXIS

- in operation on land and sea
- pointing of antennas
- customized, various payloads
- · up to 50 kg payload or customized

#### 2-AXES AND 3-AXES (4-AXES AS OPTION)

- 2 axes and 4 axes azimuth / elevation gimbals
- RPY 3-axes gimbals, high speed gimbals (up to 5'000 °/s²)
- high speed mirror stabilization systems (up to 80'000 °/s²)
- wide range of precision, < 15 μrad ... 10 mrad</li>
- light weight to heavy load platforms, gimbals with specific and exchangeable payloads
- In house design and manufacturing of advanced electronics, sensors and gimbal control with video tracker feedback, joystick control and remote control interfaces
- standard systems and customized designs



- high precision stabilized gimbals
- designed with direct drive brushless torques and direct shaft mounted angular encoders for ultra-high dynamics, high position resolution and accuracy and low wobble
- smooth stable rates over large dynamic range, suitable also for long focal length sensors
- continuous or limited rotation in azimuth and/or elevation
- sliprings for optical video link, RS422, Ethernet, discrete lines, payload power supply
- designed for helicopter environment



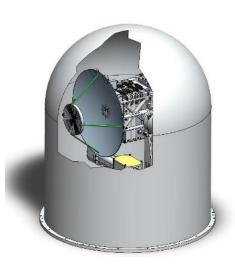
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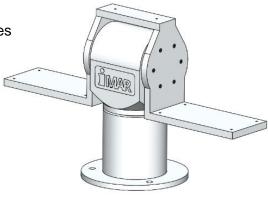
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#### 2-Axes Pan&Tilt Heads

- different weight classes
- with and without stabilization

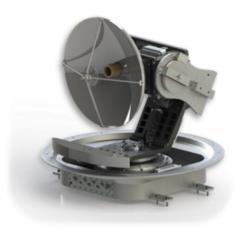




#### 1, 2 and 3-Axes Stabilized Gimbals

- lightweight
- nearly all kind of payloads
- deliverable for any application





Sky View: Stabilization of Scientific Instruments



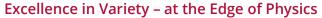




### Example for customized Solution:

Same gimbal is capable to

- carry different payloads, depending on mission
- provide video target tracking with many different cameras
- provide separate controlled optical pathes



Excellence in Variety – at the Edge of Physics



#### Variable, expandable GUI, with Interfaces to many Payload Sensors





#### Groundbreaking ToolChain for Gimbal & Control Design, System Development, Testing and Verification

- ✓ Hexapod for up to 1 ton payload
- ✓ rotatory and translatory movements, up to 50 °/s and 500 °/s² and 1 g acceleration in all spatial directions
- ✓ testing with simulated as well as with real acquired motion excitation data
- ✓ in-house design, manufacturing, testing, verification, FAT





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